Searching PAJ Page 1 of 1

PATENT ABSTRACTS OF JAPAN

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(21)Application number: 11-240522 (71)Applicant: MATSUSHITA ELECTRIC IND CO

LTD

(22)Date of filing: 26.08.1999 (72)Inventor: SAKURAI YASUHIRO

INOUE RIYUUTSUKASA

(30)Priority

Priority number: 10254787 Priority date: 09.09.1998 Priority country: JP

(54) OPERATION INSTRUCTION OUTPUT DEVICE GIVING OPERATION INSTRUCTION IN ACCORDANCE WITH KIND OF USER'S ACTION AND COMPUTER-READABLE RECORDING MEDIUM

(57)Abstract:

PROBLEM TO BE SOLVED: To obtain an operation instruction output device which converts an operation instruction corresponding to the movement of a device body by detecting the movement of the device body and distinguishing the kind of a user's action which generated the action

SOLUTION: A movement detecting part 101 detects the movement of a device body. A movement analyzing part 102 102- analyzes a movement direction, strength and the number of times from the detected movement. A user's action analyzing part 103 finds the frequency distribution of the movement from the detected movement and analyzes the kind of the user's action. A processing deciding part 104 has a storing part which stores an operation instruction corresponding to the movement direction of the device, etc., and the kind of the user's action and outputs an operation instruction corresponding to a mind outputs of the parts 102 and 103 to an information processor.



Equivalent to JP2000148351A

US00636979481

(12) United States Patent

(54) OPERATION INDICATION OUTPUTTING

DEVICE KIND CIVING ADEDATION

Sakurai et al.

(10) Patent No.: US 6,369,794 B1

	INDICATION ACCORDING TO TYPE OF USER'S ACTION				
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(*)	Notice:	Subject to any dischinact, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 0 days.			

(21) Appl. No.: 09/389,620 (22) Filed: Sep. 3, 1999

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 Foreign Application Priority Data

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 10-254787

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 Int. Cl.*
 G00G 500

 (52)
 U.S. Cl.
 345/156; 379/433.04

 (58)
 Field of Search
 345/156; 157

345/158; 382/276, 280; 379/433.04 (56) References Cited

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133994

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Primary Examiner—Rechard Hierge Assistant Examiner—Rousid Laness (74) Atterney, Agent, or Firm—Wenderoth, Lind & Pousek, L.L.P.

ABSTRACT

A motion detecting unit detects a motion of an operation indication outputting device. A motion analyzing unit analyzes a direction, setrough, and number of occurrence of the detected motion. A user action analyzing unit analyzes a type of a user's action by whatming a frequency distribution from the detected motion. As operation determining unit incitates a storing unit which siteres operation indications that each correspond to a type of the user's action and a direction and other attributes of a motion of the operation indication outputting device extacted by the user's action, and outputs an operation indication corresponding to the analyzis results by the motion snalyzing unit and user action attalyzing unit and user action attalyzing unit to an information processing appearation.

20 Claims, 22 Drawing Sheets

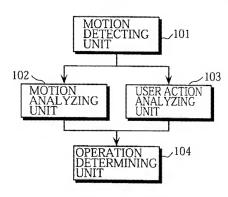
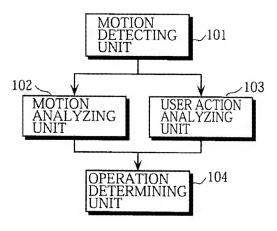


FIG. 1



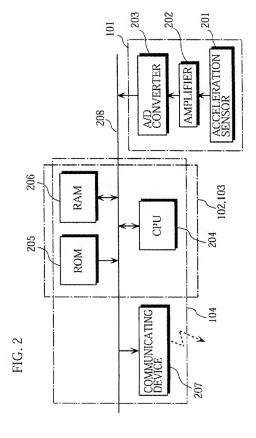


FIG. 3

FIG. 4A

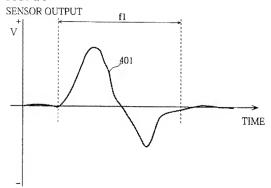
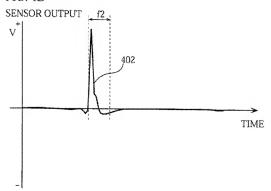


FIG. 4B



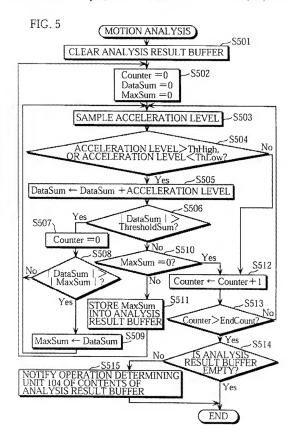


FIG. 6

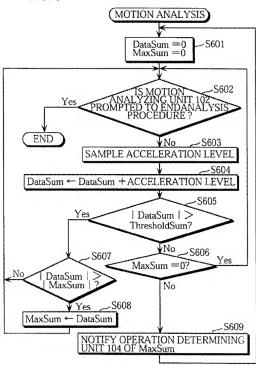


FIG. 7A

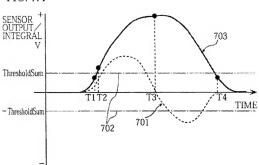
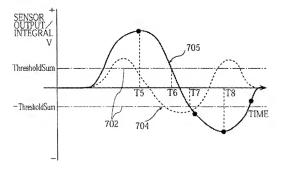


FIG. 7B



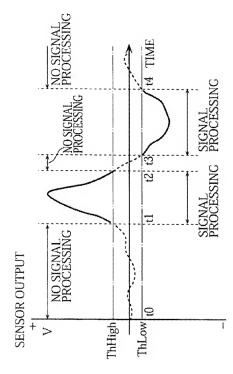
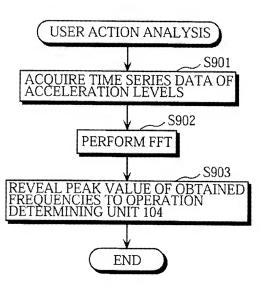
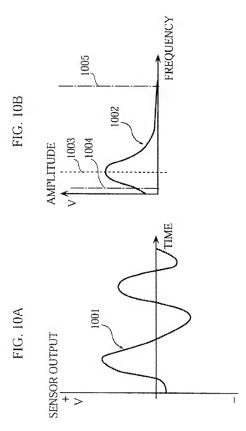
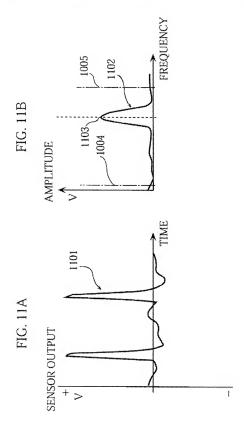


FIG. 9

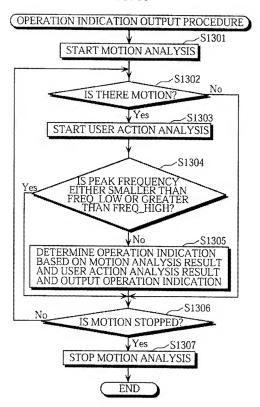






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1208 1204 1202 1205 SENSO LOW FREQUENCY POSSTIVE INEGATIVE ORBRECTION DIRECTION CONTINUITY	DOWN	LOWER	LOWER	CANCEL OPERATION	NEXT PAGE	PREVIOUS PACE	TOP PAGE	
1208 120 LOW POSITIVE	an /	UPPER RIGIT	UPPER	CANCEL OPERATION	NEXT PAGE	PREVIOUS PAGE	TOP PAGE	
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FIG. 12		EKEÓNENCA FOM			EKEÖNENCA HIGH			
\cong I	SENSOR 2							

FIG. 13



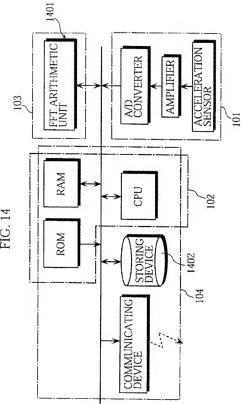


FIG. 15 208

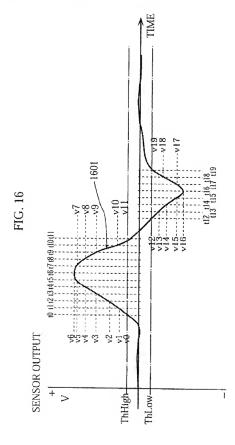


FIG. 17

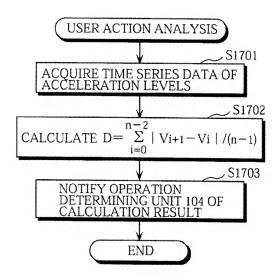
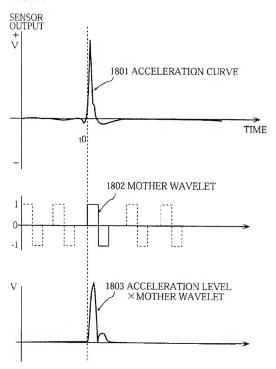
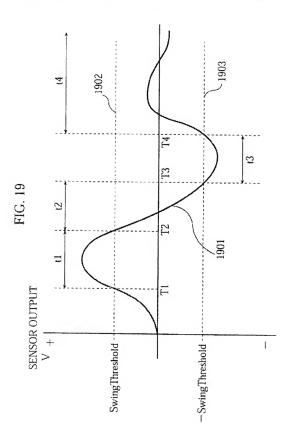
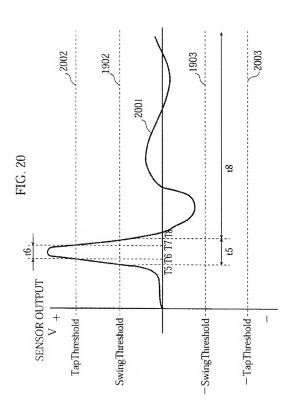
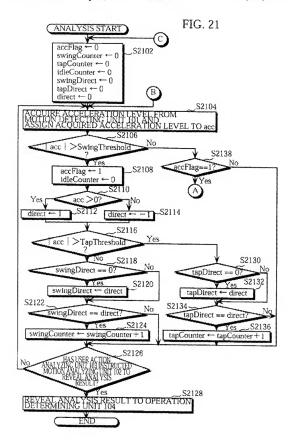


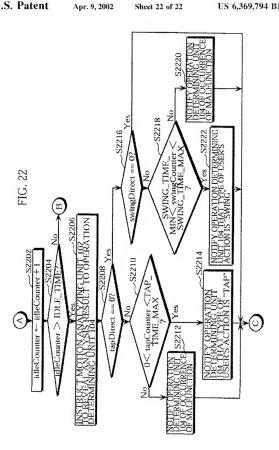
FIG. 18











OPERATION INDICATION OUTPUTTING DEVICE FOR GIVING OPERATION INDICATION ACCORDING TO TYPE OF USER'S ACTION

This application is based on an application No. 10-254787 filed in Japan, the content of which is hereby incorporated by reference.

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention relates to an operation indication outputting device for detecting a stotion of the operation indication outputing device caused by a user's action and mapatring an operation indication according to the detection result

2. Description of the Prior Art

In virtual reality and other technologies, display control and operation indication are performed by digitally coding a movement of a person with position sensors (e.g. 3SPACE system made by Polhemus, Inc.) which use data gloves or magnetic transducing techniques and inputting generated codes into a commuter. With the recent development of acceleration sensors, several techniques are disclassed whereby such sensors are incorporated into a portable information processing apparatus to detect a motion of the body of the apparatus so that information processing is performed according to the detected motion.

For instance, Japanese Laid-Open Patent Application 5-4208 discloses a device that is equipped with a sensor for detection a motion of the device and a motion analyzing unit for determining a direction, travel, and number of occurrence of movement or rotation of the device based on data 25 outpatted from the seasor, thereby designating the contours of processing according to the determined direction, travel, and ameber of occurrence of the motion. When this device is vertically and/or horizontally moved, the inside sensor detects the motion and outputs data of the motion, based on which the motion analyzing and calculates the vertical travel and horizontal travel of the device. As a result, a display such as text on a liquid crystal display panel is scrolled sideways or up and down by a number of pixels corresponding to the calculated travel, or a cursor displayed on the display panel is moved sideways or up and down by the aumber of pixels.

However, this conventional device does not distinguish certain types of actions such as "swing" and "tap" made by a user against the body of the device, so that a selection of operations which can be designated is limited. Besides, when the user socidemaily bumps the device against something while moving the device, an operation which the user does not intend may be designated by mistake

SUMMARY OF THE INVENTION

to view of the above problems, the present invention aims to provide an operation indication outputting device that can give a wide variety of operation indications while preventing malfunctions, and a computer-readable storing medium that stores a program for realizing the function of the operation indication outputting device.

The stated object can be fulfilled by an operation indication outputting device for outputting an operation indication 65 to an information processing apparatus to have the information processing apparatus perform processing based on the

outputted operation indication, the operation indication outputting device including: a storing unit for storing operation indications that each correspond to a combination of a type of a user's action and at least one of a direction, a strength, and a number of occurrence of a motion of the operation indication outputting device caused by the user's action; a motion detecting unit for detecting a motion of the operation indication outputting device caused by the user's action; a mention analyzing unb fix analyzing at least one of a in direction, a strength, and a number of occurrence of the detected motion; a user action analyzing unit for analyzing s type of the user's action that causes the detected monon: and an onipuning unit for reading, from the storing unit, an operation indicates corresponding to a combination of an analysis result by the meetion analyzing unit and an analysis nesult by the user action analyzing unit, and outputting the a.ad operation indication to the information processing apparatus.

With this construction, the operation indication outputting device can have the information processing apparatus perform various processing by identifying the type of the action made by the user against the operation indication outputting device.

Here, the motion detecting unit may detect acceleration smaller and more accurate motion detection seasons such as 28 levels of the motion of the operation judication outputting device over time, wherein the motion analyzing unit analyzes at least one of the direction, the strength, and the number of occurrence of the motion by intensiting, with respect to time, the acceleration levels outputted from the motion detection unit.

With this construction, the motion of the operation indication outputting device can be detected with low-priced acceleration sensors, and at least one of the direction, strength, and number of occurrence of the motion can be analyzed by a simple procedure.

Here, the user action analyzing unit may include a fast Fourier transform analyzing and for obtaining a frequency distribution by performing a fast Fourier transform on a curve produced by graphing the acceleration levels outputted from the motion detecting unit against time, to analyze the type of the user's action.

With this construction, the type of the user's action can be identified with respect to frequency by analyzing the fivequency distribution.

Here, the user action analyzing unit may further include an output prohibiting unit for prohibiting the outputting unit to output the operation indication if a peak value in the obtained frequency distribution is any of below a first frequency and above a second frequency.

With this construction, it is possible to prevent the infermation processing apparatus from performing wrong procossing in the event of an accident such as the user dropping. the operation indication outputting device.

Here, the user action analyzine unit may include a difkerential analyzing unit for diffeousiating, according to a predetermined capation, a curve produced by graphing the acceleration levels outputted from the motion detecting unit against time, to analyze the type of the user's action.

With this construction, the type of the user's action can be judged by a simple procedure.

Here, the user action analyzing unit may turther include an cartest prohibiting unit for prohibiting the outputting unit to output the operation indication if a mean value of differential values calculated by the shifterential analyzing unit is any of below a first threshold value and above a seasond threshold value.

With this construction, it is possible to prevent the information processing apparates from performing wrong proocssing in the event of an accident such as the user dropping the operation indication outputting device.

Here, the user action analyzing unit may include a waveler 3 transform analyzing unit for detecting specific frequency components by performing a wavelet transform on a curve pushed by graphing the acceleration levels ompatted from the motion detecting unit against time, to analyze the type of the user's action.

With this construction, the type of the user's action can be accurately specified by analyzing frequency composition.

Here, the storing unit may further store operation inducations that each correspond to an order of a plurality of types of the user's actions, wherein the user action analyzing unit further includes an action sequence analyzing unit for analyzing types of the user's actions that cause the motion, according to an order in which the detected specific forquency components appear, and wherein the outputting unit includes an order-corresponding operation indicating unit for reading, from the storing anh, an operation indication corresponding to an order of the types of the user's actions analyzed by the action sequence analyzing unit, and outputting the read operation radication to the information processing apparetus.

With this construction, a choice of operation indications which can be instructed to the information processing apparous is further diversified.

Here, the uses action analyzing unit may include a time 30 analyzing unit for measuring, for each of a plurality of reference values, time thiring which the reference value is exceeded by sheatute values of a sequence of acceleration levels anomo the acceleration levels outpotted from the motion detecting unit, to analyze the type of the user's as antina

With this construction, the type of the user's action can be specified with reference to the planality of reference values.

Here, the user action analyzing unit may further include an output probabiting unit for probabiting the outputting unit to output the operation indication if at least one of absolute values of the outputted acceleration levels is any of below a first threshold value and above a second threshold value.

With this construction, it is possible to prevent the information processing apparatus from performing wrong processing in the event of an accident such as the user dropping the operation indication outputting device.

Here, the motion detection unit may detect acceleration levels of the motion of the operation indication outputting 50 analyze the type of the user's action. device over time, wherein for each of a plurality of reference values, when the reference value is exceeded by absolute values of a resurnce of acceleration levels smoon the receleration levels outputted from the motion detecting unit. level whose absolute value first exceeds the reference value in the sequence of acceleration levels, and measures time during which the reference value is exceeded by the absolute values of the sequence of acceleration levels, thereby analyzing at least one of the direction, the strength, and the number of securence of the motion, and wherein the user action analyzing unit analyzes the type of the user's action based on the time measured by the motion analyzing unit.

With this construction, the type of the oser's action can be identified by simply measuring a period for each of the 65 plurality of reference values during which absolute values of detected acceleration levels exceed the reference value. In

doing so, the operation inducation outputting device can have the information processing apparatus execute various

there, the plansify of reference values may be made up of a first reference value and a second reference value larger than the first reference value, wherein the user action analyzing unit includes an output prohibiting unit for prohibiting the outputting unit to output the operation redication, any of if time during winch the first relerence value is exceeded 26 is shorter than predetermined first time and if time during which the second reference value is exceeded is longer than predetermined second time.

With this construction, it is possible to prevent the information processing apparatus from performing wrong procussing in the event of an accident such as the user dronoing the operation indication outputting device.

Here, the first reference value may be set at a value corresponding to an acceleration level which is to be detected when the user swings the operation indication outputting device, wherein the second reference value is set at a value corresponding to an acceleration level which is to be desected when the user taos the operation indication outputting device, and wherein the user action analyzing unit analyzes whether the type of the user's action is "swing" or "tap"

With this construction, the type of the user's action can be specified as "swing" or "tap" by setting the first and second reference values respectively at values corresponding to, for example, 1 G and 2.5 G (G denotes the acceleration of

Here, the mestion detecting unit may detect angular accelcration levels of the motion of the operation indication outputting device over time, wherein the movies analyzing unit analyzes at least one of the direction, the strenoth, and the number of occurrence of the motion by integrating, with respect to time, the angular acceleration levels outputted from the motion detecting unit.

With this construction, the operation indication outputting device can also analyze a rotary motion originated from the user's wrist when the user rotates the operation indication outputting device by hand, thereby farther diversifying a choice of operation indications which can be outputted to the information processing apparatus.

Here, the user action analyzing unit may include a fast Fourier transform analyzing unit for obtaining a frequency distribution by performing a fust Fourier transform on a curve produced by graphing the angular acceleration levels outsetted from the motion detecting any assists time, to

With this construction, the type of the user's action can be identified on the basis of an analysis of the frequency

Here, the motion eletecting unit may detect angular secolthe motion analyzing unit analyzes a sign of an acceleration 33 eration levels of the motion of the operation indication outputting device over time, wherein for each of a plurality of reference values, when the reference value is exceeded by absolute values of a sequence of angular scoderation levels among the angular acceptration levels corosited from the motion detecting unit, the motion analyzing unit analyzes a sign of an angular acceleration level whose absolute value first exceeds the reference value in the sequence of angular acceleration levels, and measures time during which the reference value is exceeded by the absolute values of the sequence of angular acceleration levels, thereby analyzing at least one of the direction, the strength, and the mimber of occuprate of the motion, and wherein the user action

malyzing unit analyzes the type of the user's action based on the time measured by the motion analyzing unit

With this construction, the type of the user's action can be identified by simply measuring a period for each of the plaratity of reference values during which absolute values of detected angular acceleration levels exceed the reference value. As a result, the operation indication outsuiting device can have the information processing apparatus perform various processing,

The stated object can also be fulfilled by an operation indication outputting device which is incorporated into a mobile phone that is an information processing apparatus, wherein a processing mode of the mobile phone is changed according to an operation indication outputted from an outputting and of the operation indication outputting device.

With this construction, the operability of the mobile phone which incorporates the operation indication omputting device is unproved.

The stated object can also be fulfilled by a mobile phone a that incorporates an operation indication outputting device for optimiting an operation indication to the mobile phone to have the mobile phone perform processing based on the autputted operation indication, the operation indication outputting device including; a storing unit for storing operation indications that each correspond to a combination of a type of a user's action and at least one of a direction, a strength, and a number of occurrence of a motion of the operation indication outputting device caused by the user's action; a motion detecting unit for detecting a motion of the operation of indication outputting device caused by the user's action; a motion analyzing unit for analyzing at least one of a direction, a strength, and a number of occurrence of the detected motion; a user action analyzing unit for analyzing a type of the user's action that causes the detected motion; 24 and an outputting unit for reading, from the storing unit, an operation indication corresponding to a combination of an analysis result by the motion analyzing unit and an analysis result by the own action analyzing and, and outputting the read operation indication to the mobile phone, wherein a processing mode of the mobile phone is changed according to the operation indication outputted from the omputting

With this construction, the operability of the mobile phone which incorporates the operation indication on puttung device is unproved.

The stated object can also be fulfilled by a computerreadable storing medium storing a program executed by an operation indication outpurting device that is equipped with a detecting unit for detecting a motion of the operation so indication outputting device caused by a user's action and outputs an operation indication to an information processing apparatus to have the information processing apparatus perform processing based on the outputted operation indication, the program including: a motion analyzing step 38 for analyzing at least one of a direction, a strength, and a number of occurrence of the motion detected by the detecting unit; a user action analyzing step for analyzing a type of the user's action that causes the detected motion; and an mituating step for reading, from an storing unit which stores operation indications that each correspond to a combination of a type of the user's action and at least one of a direction, a strength, and a mumber of occurrence of a motion of the operation indication outputting device caused by the user's action, in operation indication corresponding to a combina- 55 operation indication outputing device; tion of an analysis result obtained in the motion analyzing step and an analysis result obtained in the user action

analyzing step, and outputting the read operation indication to the information processing apparatus

With this construction, the operation indication outputting device equipped with the mession desecting unit can be nendered a device that can output a wide variety of operation zaritentini.

BRIEF DESCRIPTION OF THE DRAWINGS

These and other objects, advantages and features of the invention will become apparent from the following description thereof taken in conjunction with the accompanying drawings that illustrate a specific embediment of the movestion. In the drawings:

FIG. I shows the configuration of an operation indication outputting device of the first embodiment of the present invention;

FIG. 2 shows the hardware construction of the operation indication outputting device;

FIG. 3 shows the appearance of the operation indication outputting device and the placement of a motion detecting unit 101:

FIG. 4A shows an acceleration curvs ompaned from an acceleration sensor of the motion detecting unit 101 when 25 the user swings the operation indication computing device

FIG. 4B storws an acceleration curve outputted from an acceleration sensor of the motion detecting unit 101 when the user tans the operation indication outsistting device once;

FIG. 5 is a flowchart showing an example of motion analysis by a motion snalvzing unit 1012 of the operation indication outputting device;

FIG. 6 is a Bowchart showing another example of motion analysis by the motion agalyzing unit 102;

FIG. 7A shows an integral curve for acceleration levels obtained by the motion analyzing unit 102 when the user swings the operation indication outputting device once;

FIG 7B shows an integral curve for acceleration levels obtained by the motion analyzing unit 102 when the user swings the operation indication outputting device cominuqualt:

FIG 8 shows threshold values used for acceleration levels outputted by the nation detecting unit 101,

FIG. 9 is a flowchart showing user action analysis by a user action analyzing unit 103 of the operation indication outputing device;

FIG. 10A shows an accompanion curve outputted from the motion detecting unit 101 when the user swings the operation indication outputting device:

FIG. 19B shows a frequency distribution curve obtained by the user action analyzing unit 103 performing a FUT on the seceleration curve in FIG. 10A,

FIG. 11A shows an acceleration curve outputted from the medion detecting unit 101 when the user taps the operation indication outputting device;

FIG. HB shows a frequency distribution curve obtained by the user action analyzing unit 103 performing a FFT on the acceleration curve in FIG. 11A:

FIG. 12 shows the consents of an operation determination table stored in an operation determining unit 104 of the operation indication outputting device;

FIG. 13 is a flowchart showing the overall operation of the

FIG. 14 shows the hardware construction of a variant of the first embodiment.

FIG. 15 shows the hardware construction of a variant of the first embodiment;

FIG. 16 shows the details of user action analysis by the user action analyzing unit 103 of the operation indication amputing device in the second embodiment of the present succession.

FIG. 17 is a flowchart showing the user action analysis by the user action analyzing unit 103 of the second embodiment;

FIG. 18 shows the process of a wavelet transform performed by the user action analyzing unit 103 of the operation indication outputting device in the third embodiment of the present invention;

FIG. 19 shows an acceleration curve outputted from the autimn deacting until 101 of the operation indication outputing device in the flowth embodiment of the present avocation when the user swings the operation indication computing device once;

FIG. 20 shows an acceleration curve outputted from the motion detecting unit 101 when the user taps the operation indication outputting device once;

(1) TIG. 21 is a flowchart showing motion analysis by the motion analyzing unit 102 in the fourth embodiment; and FIG. 22 is a flowchart showing user action analysis by the 25.

user serion analyzing unit 103 in the frienh embediment.

DESCRIPTION OF THE PREFERRED EMBODIMENT(S)

The following is a description of the embediments of the 30 present invention with reference to the figures.

First Embodiment

FIG. I shows the configuration of an operation inducation outputting device of the Brist embodiment of the present invention. The device includes a mution electring unit 101, a motion studying unit 102, a user action analyzing unit 103, and an operation determining unit 103, and an operation determining unit 103, and an operation determining unit 103.

FIG 2 shows the hardware construction of this operation michaelon outputing device. The motion detecting that 10 is implemented by an acceleration sensor 201, a signal amplifier 202, and an ArD (analog-to-digital) conventer 200. The motion soutpuing mint 103 and the user action analyzing and 103 are implemented by a CPU 2043, a ROM 205, and a RAM 206. The operation determining mint 104 is implemented by the CPU 2044, the ROM 205, the RAM 206, and a communicating device. 207 The ArD conventer 203, the CPU 2044, the ROM 205, the RAM 206, and the communicating device 207 are connected to a bus 208.

The medion deacting unit 01 samples acceleration levels in the acceleration exerse 201 a predetermined time intervals of, for instance, Vess second, amplifies analog voltage changes in the amplifier 202, converts the amplification ensuit to digital data in the AD converter 203, and origins set the digital data to the motion analyzing unit 102 and user section analyzing unit 103 via the two 208.

FIG. 3 shows the appearance of the operation indication computing device and the placement of the acceleration sensor 201 of the motion detection unit 101.

In the figure, the motion detecting unit 101 has two the figure, the motion detecting unit 101 has two and the first particular detection sensors and and 302 which are endeaune. 303. The acceleration seroes 301 and 302 are placed respectively on detection sexs 305 and 306 that are off-legicular to each other, to dotted motion on a two-sidensessarial plane parallel to the front 304 of the enclosure 303.

Here, to detect notion of the enclosure 303 in a single direction the motion detecting unit 101 may include only an acceleration sensor, while so direct notion of the enclosure 303 in a three-dimensional space another acceleration sensor may be placed on a detection axis orthogonal to the detaction axis 303 and 306, in addition to the acceleration sensors 301 and 302.

Also, an action stan button 368 may be placed in the surface 367 of the enclosure 363 to detect motion of the medicane 363 while the user is pressing the button 368.

Further, a contact sensor for sensing contact by the user may be equipped in the enclosure 363 to detect motion of the caclosure 363 white the user is holding the enclosure 363.

Instead of being equipped with the above button and acceleration sensers, the operation indication outputing, device may analyze motion of the enclosure 303 only when an intput level of the acceleration sensor 201 exceeds a predetermined threshold value (ThFfighThLow).

FIGS. An and 4B show this uniquited from the motion detecting with 101 Curve 401 slown in FIG 4A is an acceleration curve outputted, for example, from the accelcation sensor 302 when the enclosure 303 is awarg once in the positive detection of the detection axis 309 and then stopped. The inverse of time taken for this motion, represented by frequency II, is accural 1-54 Bz.

Curve 402 shown in F05. 4B is an acceleration curve outputted, for example, from the secoleration sensor 301 when the enclosure 303 is tapped once in the positive direction of the detection axis 305. Frequency 12 in this case is around 100–150 Hz.

Note here that to swing the enclosure 303 once is to move the enclosure 303 from one point to another, while is tay the enclosure 303 once is to strike the enclosure 303 with a strike the enclosure 303 with a

Thus, a frequency differs depending on a type of an action, such as "swing" or "tap", made by the user against the enclosure 303. The present invention reflects such differences of types of the user's actions on the conjents of an operation andication to be outputted.

The motion analyzing unit 102 checks sign, magainede, and influction point in acceleration data osupasted from the motion eletecting unit 101 to analyze a direction, strength, and mumber of occurrence of a motion, and passes the analysis result to the operation determining unit 104.

As is evident from the hardware construction in FIG. 2, the motion analyzing unit 102 performs the analysis via the CPU 204 occording to a program strend in the ROM 205.

The analysis procedure by the motion analyzing and 102 is explained below with reference to FIGS 5 and 6.

The analysis procedure in FIG 5 is as follows, Here, the RAM 206 is used as a buffer for storing an analysis result.

In this example, acceleration levels sequentially instputed from the motion detecting unit 101 are represented by dashed line 701 in FIG. 7A.

The mesion analyzing unit 102 commences its motion analysis once the user has pressed the button 308 or the output from the acceleration sensor 301/302 has changed.

The motion analyzing unit 102 first clears the analysis result buffer 206 (S501) and initiatizes variables DataSuur, MaxSum, and Counter to 0 (S502).

The motion analyzing unit 102 from acquires an acceleration level outputted from the motion detecting unit 101 (\$503) and judges whether the acceleration freel is above predetermined threshold value Thiligh (on the plus side) and whether the acceleration level is below predetermined whether the above threshold value filtow (on the minus ade) (5890-fi fi the acceleration level is neither greater than Thiltigh not smaller than Thiltow, the procedure pronoceds to step \$\$12.00 Otherwise, the motion analyzing unit 102 adds the acceleration fevel to DataSatum (\$\$505) here, paraSatum is used for evaluating the integral of acceleration levels and so approach seven the acceleration fevel in the processes accessed to the acceleration fevels and so approach sevels.

The motion analyzing mit 102 text judges whether the absolute value of DataSum exceeds threshold value ThresholdSum is represented by single point chained line 702, whereas DotaSum is represented by velocity curve 708.

When the absolute value of DataSum exceeds Threshold-Sun at time 12 or 104 ft. 74, the motion analyzing until 102. ¹⁵ initializes Cosmer to 0 (\$5007) and judges whether the absolute value of DataSum exceeds the absolute value of MaxSum (\$508). If the absolute value of DataSum does not exceed the absolute value of DataSum does not exceed the absolute value of MaxSum, the procedure returns to step \$500. Ultravisies, the metion analyzing unit 102 assigns DataSum to MaxSem (\$5090) and returns to step \$500. The process from step \$503 to step \$509 is repeated until time 13 in the present example.

If the absolute value of DataSum does not exceed ThresholdSam in sape \$506 as in the case of time T1 or time T4, the motion analyzing unit 102 judges whether MaxSumed (\$5510). If MaxSumed as in the case of time T4, the motion analyzing imit 102 writes MaxSum into the analysis result buffer 206 (\$511) and neurons to step \$580. If MaxSumed, on the other band, the motion analyzing unit 102 increments Counter by 1.58512.

The motion analyzing unit 102 there judges whether consider exceeds specified value Endforcum (SS13). When Counter-REdeffourth, the procedure returns to step SS03 when Counter-REdeffourth, the procedure returns to step SS03 when Counter-REdeffourth, the motion analyzing unit 102 judges whether the analysis result buffer 206 is empty list motion analysis procedure units Otherwise, the motion analysis procedure unit Otherwise, the motion analyzing procedure unit 102 notifies the operation determining unit 104 of the storage contents of the analysis result buffer 206 (SS15) and easts the motion analysis grocedure.

Here, EndCount is specified based on a sampling time interval in step \$593 and adjusted so that the analysis procedure ends when a few seconds lapse before time TI or after time TI. EndCount may also be altered by the user. MaxSum onthing to the one-time determination until 104 in

MaxSum notified to the operation determining unit 104 in this example is the integral at time T3 in FIG. 7A and denotes the maximum velocity when the enclosure 303 is swame.

The sign of MaxSum shows whether the euclosure 303 was swang in the predictor direction or file negative direction, while the magnitude of MaxSum as show whether the euclosure 303 was swung lightly or strongly. Also, the fact that there is only one MaxSum in FIG. 7A denotes that the 58 euclosure 303 was swang much such services on the state of the state

On the other hand, when a sequence of acceleration levels exponented by dashed line 704 in EIG. 7B is outputted from the motion detecting and 101, the motion analysis procedure is performed as fullows.

In this case, after DataSum at time TS is written into the analysis result infect 200 is a Maxim in step SSLI, between time T6 and time 17 the absolute value of velocity curve 705 does are coxeed Thresholdsum 702 and so Counter is interemented by 1 in step SSLI for certal acceleration level 50 during this period. Since Counter those not exceed Emfo Counter those not exceed Emfo Counter the Counter those not exceed Emfo Counter the Counter Counter those not exceed Emfo Counter the Counter Counter Counter and everywalth DataSum

at time 'F8 is written into the analysis result buffer 206 is MaxSum in step S511.

Thus, for the sequence of acceleration levels shown in FIG. 7B, the motion analyzing unit 102 octilies the operation determining unit 104 of both positive MaxSum and negative MaxSum.

When revealing the storage consents of the analysis result buffer 206 to the operation determining unit 104 in step 8515, the motion analyzing unit 102 also untitles which of the secoleration sensors 301 and 302 the revealed analysis result is derived from

While the medion analyzing and 102 has received one acceleration level at a time from the median detecting unit 101 in step 5.503, instead a sequence of acceleration levels may attogether be buffered in the RAM 206 to be later extracted one by one.

Also, as shown in FIG. 8, step S504 can be omitted if the notion detecting unit. 101 is designed to output an acceleration level (with signal processing) when an output of the acceleration seasor 301,302 is either greater than ThHigh or smaller than ThLow.

In such a case, the motion detecting unit 101 outputs acceleration levels to the motion analyzing unit 110 2 and user scrion analyzing unit 110 during 11-42 and 13-44, and drass and output acceleration levels during 10-11 and 12-43 and after 14.

Such a process by the motion detecting unit 101 or step S504 by the motion analyzing unit 102 is effective to award unwanted processing for error acceleration levels of small mapphades detected by the acceleration sensor 301,302.

On the other hand, the analysis procedure in FIG. 6 that does not use the analysis result buffer 206 is as follows.

The motion analyzing unit 102 files initializes variables. Datakims and Maxism to 0 (5801) and judgess whether the motion analyzing unit 102 is prompted to end the procedures (5802). If so, the motion analyzing unit 102 ends the motion constitution of the motion analyzing unit 104 ends the procedure when he uses strays pressing the bitton of some for other the operation determining unit 104 outputs an operation includesion for an information processing approaches.

If not yet prompted to end the procedure, the motion analyzing unit 162 samples an acceleration level outputted from the motion detecting unit 161 (\$603) and adds the scorlegation level in Dardshim (\$604).

The motion analyzing unit 102 then judges whether the absciute value of DataSiam coxech threshold value TheelioldSunt (S608). If the absolute value of DataSiam does not
coccod ThresholdSunt, the motion analyzing unit 102 judges
whether MaxSura-0 (S606). If MaxSura-0, the procedure
returns to step 5062, while if MaxSura-0, the procedure
proceeds to step 5062, while if MaxSura-0, the procedure
proceeds to step 5062, when the distribution is the procedure
proceeds to step 5069. When, on the other hand, the absolute
value of DataSou neceeds ThresholdSum in site 5068, the
meion analyzing until 102 further judges whether the absolite value of DataSoura occeeds the absolute
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The motion analyzing unit 102 lastly notifies the operation determining unit 104 of MaxSun and returns to step \$691.

The difference between the analysis procedure in FIG. 5 and the analysis procedure in FIG. 6 that uses the analysis result buffer 206 is merely that maximum and minimum

values of MaxSum are either sequentially or concurrently revealed to the operation determining unit 164, so that they do not assentially differ.

Meanwhile, the user action analyzing unit 103 operates as

On prompted to commence user action analysis by the mortism analysis, put 102, the worse action analysis by the mortism analysis, put 102, the worse action analysis and the production of the mortism of past value from the order (term) and the past value from the order (term) and the content of the operation determination at the and outquist the read twee soles and neveals a peak value of obtained frequencies to the separation activation in the information processing apparatue with the communicating device 207. The communicating which the communicating devices are considered to the communication of the

Here, if the peak value is smaller than a predetermined frequency (FREQ_LOW) on the low frequency whole or geneter than a predetermined frequency (FREQ_HIGH) on the high frequency sick, the user action analyzing unit 183. ¹⁵ prohibits the operation determining unit 104 to compil an operation indication.

The user action analysis by the user action analyzing unit 143 is executed via the CPU 264 according to the program stored in the ROM 205, in the same way as the motion 26 analyzing unit 102.

FIG. 9 is a flowchart showing the user action analysis procedure by the user action analyzing unit 103.

The user action analyzing unit 103 acquires time series data of acceleration levels outputted from the motion detecting unit 101, when prompted by the motion analyzing unit

102 to start the user action analysis (S901). The user action analyzing unit 103 then performs a FFT on the acquired scooleration curve to obtain a frequency so distribution (S902).

FIG. 10A slaws socileration curve 1001 generated when the user continuously swings the enclosure 303, whereas FIG. 10B shows frequency distribution curve 1002 orbatised by performing a FFT on acceleration curve 1000. Peak point 1003 of finemency distribution curve 1002 is of 15–36.

FIG. 11A shows acceleration curve 1101 generated when the user taps the enclosure 303 twice, whereas FIG. 11B shows frequency distribution curve 1102 obtained by parforming a FFT on acceleration curve 1101, Peak point 1103 and frequency distribution curve 1102 is of 100-150 Hz.

The user action nativating unit 103 notifies the operation determining unit 104 of a frequency at the main peak point of the obstance thequency distribution curve and an acceleration season that detected the portional acceleration (S903) as nector completing the proceeding.

It should be noted that in step S963 when the peak point of the obtained frequency distribution curve is below frequescy FREQ_LOW on the low frequency side (shown by Single point chained line 1904) or above frequency PREQ... HIGH on the high frequency side (shown by single point chained line 1005) in FIG. 10B or 11B, the user action matyzing unit 103 probibits the operation determining unit 104 to output an operation indication, instead of revealing the peak frequency to the operation determining unit 184. FREQ LOW 1964 is set at 1 Hz for example. Suppose the caclosure 303 placed on an inclined surface moves accidentally. In such a case, a frequency distribution whose neak noint is below FREO LOW is detected. Meanwhile, FREQ_HIGH 1005 is set at 200 Hz for example. Suppose 50 the enclosure 303 is drooned or burnoed against something. In such a case, a frequency distribution whose peak point is above FREQ_HIGH is detected. With the use of FREQ_ LOW and FREQ_HIGH, it is possible to prevent the operation determining unit 164 from outputting a wrong 55 operation indication to the information processing apparatus in the event of socidental movements such as above.

The operation determining unit 104 holds an operation determination table which has been stored in the ROM2 205 in alwayers. Based on MaxSum received from the motion analyzing unit 102 and a peak value of a frequency distribution received from the user action analyzing unit 102 and a peak value of a frequency distribution received from the user action analyzing unit 104, the operation determining unit 104 reads an operation indication corresponding use the received MaxSum and peak value from the operation determining that has an operation indication to the information protessing apparatus via the communicating device 207. The communicating device 207 outputs an infrared signed expressing desperation indication to a light receiving not (not illustrated) of the information processing apparatus cia an infrared transmission line, through an aperture on the from 304 nf the enclosure 203.

FIG. 12 shows the contents of the operation determination table 1201. Sensors 1 and 2 respectively correspond to the acceleration sensors 301 and 302.

When a peak frequency partitled by the user action analyzing until 103 for sensor 1 is no generic than on exhibitshed value such as 50 Hz, the operation determining unit 104 looks at "low frequency" 1202, whereas the peak frequency is greater than the established value, the operation determining unit 104 looks at "light frequency" 1203.

Alsa, when MaxSum unsilted by the motion analyzing until 102 is a positive value while a peak frequency unified by the next action analyzing until 103 for sensor I is no greater than the established value, the operation determining until 104 looks at 2 positive during the control of the control of the many of the control of the contro

Assume a peak value 6 Hz of frequencies detected by assure 1 is onfided from the user action analyzing mst 103 and a positive value of MaxSura is notified from the motion analyzing unit 102, which no notification is made fee sensor 2. Then "mp" 1208 corresponding to "positive direction" 1204 in "loss frequency" 1202 of sensor 1 and "ft" of sensor 2. 2 is read as an operation indication and outputed to the information processing apparatus via the communicating device 207.

Assume, on the other hand, a peak frequency 2 Hz and a positive value of MaxSum are nutified for sensor 2 while no so notification is made for sensor 1. From "right" 100 corresponding to "0" 1207 of sensor 1 and "positive direction" in how frequency" of sensor 2 is read as an operation indication and outputs of the information processing arguments.

Thus, with the user's action of synaging the enclusive 303 st that contains the operation indicated neutraling device, it is possible to indicate the information processing apparatus to move a cursor or a display on a display screen of the information processing apparatus in the same direction as the enclosure 308.

50. As is evident from the operation determination stable 1201, the operation elementing until 40 can indicate any of 7 operations for one season, by distinguishing high frequency and low frequency based on data given from the user science analysing until 103 and further distinguishing as motion (*O*), positive direction, negative direction, and positive-negative continuity based on data given from the motion analysing until 102. Accordingly, when two separative properties of the continuity of the contin

are meanted is the operation indication outputting device, the operation determining unit 104 can have a choice of 49 operation indications as the maximum.

In the present embodiment, however, to establish intuitive correspondence between the user's action and an operation. of the information processing apparatus, 16 operation indications are provided that are made up of move indications (un, down, right, upper right, lower right, left, upper left, lower left, previous page, next page, top page), display indications (zoom in, zoom out), and commands (cancel operation, reexecute operation, select).

The overall operation of the operation indication outputtime device of the first embadiment is explained below with reference to FIG. 13.

Prompted by the user pressing the button 308 or the like, the motion detecting unit 101 starts motion detection and the motion analyzing unit 102 is instructed to commence motion analysis (S1301).

The motion analyzing unit 102 judges whether there is a 20 motion (\$1302). If there is a rootion, the motion analyzing unit 102 instructs the user action analyzing unit 103 to start user action analysis (\$1303). Otherwise, the procedure proceeds to step \$1306.

On instructed to start the user action analysis, the user 35 action analyzing unit 103 analyzes a frequency distribution and judges whether a peak value in the frequency distribution is below FREO LOW and whether the peak value is above FREQ_HIGH (\$1304). If the peak value is either smaller than FREQ_LOW or greater than FREQ_HIGH, so but calculates the amount of change in acceleration level to the procedure proceeds to step \$1306. With this indeement, a malfunction of outputting a wrong operation indication is asolded when the enclosure 303 is accidentally dropped or bimped against something.

greater than FREQ_HIGH, the operation determining unit 104 determines the contents of an operation indication based on the motion analysis result and user action analysis result and coupets the determined operation indication to the information processing apparatus (\$1365).

The motion detecting unit 101 indges whether the motion is stopped (\$1306). If the motion has not been stopped, the procedure returns to step \$1302. Otherwise, the motion desecting unit 101 instructs the morion analyzing unit 102 to step the motion analysis (\$1307) to complete the procedure.

While in the above embodiment the user action analyzing unit 103 has been implemented via the CPU 204 according to the program for performing a FFT in the ROM 205, the FFT may be performed concurrently with the motion analysis of the motion analyzing unit 102, by equipping a FFT 50 arithmetic unit 1401 in the operation indication outputting device as shown in FIG. 14.

Also, while the operation desermination table 1201 has been stored in the ROM 265 in advance in the above so embodiment, the operation determination table 120 may instead he saired in a storing device 1402 included in the operation determining unit 164 so that each user can set and dynamically change the contents of the table independently.

Though the operation determining unit 104 has sorted a peak frequency notified from the user action snatyzing unit 103 as high frequency or low frequency in the above embodiment, the peak frequency may instead be sorted under three categories to further diversity operation unlicalions.

Though the operation determining and 164 has checked only a sign of MaxSun notified from the mation analyzing

unit 102 in the above embodument, the operation determining unit 104 may also check an absolute value of MaxSum to incorporate strength of the user's action into criteria for descratining an eneration indication.

While an operation indication has been omputed from the communicating device 207 to the information processing apparatus in the hardware construction in FIG. 2, it is also possible to connect the bas 208 to the information processing apparatus to control the display screen and the like of the information processing apparatus, as shown in FIG. 15.

In the above embodiment, the user actust analyzing unit 103 has prohibited the operation discernining unit 104 to output an operation indication when a peak frequency is above FREQ_HIGH on the high frequency side. At this point, MaxSum analyzed by the motion analyzing unit 102 corresponding to the peak frequency may be stored as a record on accidents of the operation indication outputting device. By keeping such a record, it is possible to analyze a cause of a failure of the operation indication outputting device in the evens of the device being dropped or bumped agginst something.

Second Embosiment

The following is a description of an operation indication outputting device of the second embodiment of the present invention. This operation indication outputing device has a configuration similar to the first embodiment, except that the user action analyzing unit 103 here does not perform a FFT determine a type of the user's action

The user action analyzing unit 103 acquires time series data (acceleration curve) 1601 of acceleration levels shown in FIG. 16 from the motion detection unit 101 and calculates If the peak value is neither smaller than FREQ_LOW nor 35 8 mean value of a sequence of differential values divid than each represent the amount of change in acceleration level per unit of time. When the absolute value of an acceleration level exceeds the error level (i.e. when the acceleration level is either greater than ThHigh on the plus side or smaller than ThLow on the minus side), voltage v proponional to the acceleration level is outpetted from the motion detecting unit 101 at certain sampling intervals (such as 2 mscc). Which is to say, dt is constant, so that in each sampling the absolute difference (iv1-vtf, lv2-vtf, lv3-v2l, . . . lv19-45 v18h in acceleration level (voltage) is calculated and a mean value of the calculated absolute differences is revealed to the operation determining unit 104. Provided a sampling points are present within one sequence for which user action analysis is executed, output D is found as follows:

(where a>1)

When a sequence of acceleration levels outwated from the motion detecting unit 101 forms a gentle acceleration curve as in FIG. 4A, mean value D of differential values calculated in Equation 1 is small, while when the sequence of acceleration levels forms a share acceleration curve as in FIG. 4B, mean value D of differential values calculated in Equation 1 is large. The operation determining unit 104 compares differential mean value D outpetted from the user 55 school analyzing unn 103 with a predetermined value to indge whether the user's action belongs to low frequency of slowly swinging the enclosure 303 or high frequency of impling the enclosure 383. Based on this judgement, the operation determining out 104 specifies an operation indication in the operation determination table 1201 in FIG. 12.

Here, if differential mean value D calculated in Equation 1s shelver productionmixed threaded value ACCEL_ILOW or 8 show productermined threaded value ACCEL_ILOW or 8 show predetermined threshold value ACCEL_ILOH, the user action analyzing unit 104 ro-billist the operation determining unit 104 to output an operation indicasion. ACCEL_ILOW and ACCEL_ILOW and PRED_ILOH in the first embeddinent and are used for proventing the cutumpt of a wrong operation indication caused by noise or the user dropping or bumping the enclosure 30 the processing the conclusion.

ACCEL_LOW and ACCEL_HIGH are set with reference to a maximum output value of the acceleration sensor if 301,302. For instance, setting 30 and 30 to fibe maximum output value respectively as ACCEL_LOW and ACCEL_HIGH can eated operation indication output processing for an actuatively slow or intense motion.

The user section analysis by the user section analyzing unit. 20 103 of the present embodiment is explained below with reference to FIG. 17.

The user action analyzing unit 103 acquires fine series data of acceleration levels (S1701), calculates mean value D of differential values according to Equation 1 (S1702), and 28 gives mean value D to the operation determining unit 104 (S1703), before completing the analysis procedure.

The overall operation of the operation inducation outputting device of the second embodiment differs with both at embodiment slower in PR. 13 donly in that in step \$1304 the so user action analyzing unit 163 judges whether differential areas value D is below ACCEL_HOW and whether differential mean value D is showe ACCEL HORD.

Third Embodiment

The following is a description of an operation indication outputting device of the third embodiment of the present incontron. Though this operation indication compating device has ranging the same configuration as the first embodiment, the analysis neithed used by the user action analyzing until 103 differs with the first embodiment. While in the first embodiment the user action analyzing until 103 differs with the first embodient. While in the first embodiment the user action analyzing until 103 the preformed a PPT on an acceleration curve outputted from the motion detecting until 107 to obsar a frequency lyring until 108 performs a sweeter transform to unabyze whether an acceleration curve outputted from the motion detecting until 108 small per of high frequency components are low frequency components, the analysis result then being given to the operation determining until 104.

A wavelet transform is a kind of filter that extracts only a waveform similar to a producentional waveform. For details on the wavelet transform, see C. R. Chrif (1997) Wavelets: A Mathematical Tool for Signal Analysis published by 58 Society for Industrial & Applied Mathematical.

The wavelet transform is examplified below with reference to FIG. 18.

In the figure, on receiving acceleration curve 1801 from the motion detecting until 101, he user action analysing unit 103 parallelly moves mother wavelet 1802 of discettion target frequency (unit as 100 Hz) in the time taxis and calculates product 1803 of mother wavelet 1802 and each acceleration level. Here, a square wave is used as mother awalet 1802. A waveform starting from turn 10 in accel-1802 and the starting from turn 10 in accel-1802 and the starting from turn 10 in accel-1802, and the product of method wavelet 1802, and each

acceleration level of this waveform is of large misitive value. if, on the other hand, a waveform of an acceleration curve greatly differs with mother wavelet 1802 such as in the case of an acceleration curve of a few hertz in frequency, both positive and negative products are found, so that summation of a sequence of such products yields a value close to 0, indicating that the acceleration curve does not have a waveform of the detection target frequency. In contrast, when a wavelet transferor is performed using a mother wavelet of 5 Hz in frequency, a waveform of an acceleration curve of low frequency close to 5 Hz can be detected, Therefore, the user action analyzing unit 103 performs the analysis using a plorality of mother wavelets of high frequencies of around 100 Hz and a plurality of mother wavelets of low frequencies of around 5 Hz and outputs the analysis result to the operation determining unit 194

Since a wavelet transform detects a strength and point of appearance of an acceleration curve, it can also be used for motion analysis by the motion analyzine mait 162. Also, if the user's action involves different frequencies such as when the user first swings the enclosure 303 which is a motion of low frequency and then taps the enclosure 303 which is a motion of high frequency, such an action by the user is analyzable with a wavelet transform, so that the operation determining unit 104 can appropriately determines an operation indication for such a combination of motions. Further, in conducting user action analysis the user action analyzing unit 103 may perform a wavelet transform to detect high frequencies and perform the differential method of the second embodiment to detect low frequencies. Also, forquency bands to be detected are not limited to a high frequency band and a low frequency band but three or more frequency bands may be targeted for detection depending on the processing canability of the operation determining unit 35 104. While the square wave has been used as the mother wavelet he performing a wavelet neasform in this embodiment to reduce a calculation amount when authinfying the mother wavelet and the acceleration curve to be analyzed, instead the Dashuchies wavelet may be used to improve detection accuracy.

Fourth Embodiment

The following is a risextraption of an operation imilication outputing device of the fourth embediment of the present invention. Although the configuration of this operation indiction outputing device is sentiate to the first embediment, the mini difference lies in that the stoom analyzing and 102 and the user action analyzing and 102 exchange their analysis results in the fourth embedience. The following description focuses on the difference within to other embediences.

The motion analyzing unit 102 compares can't necessitation level sequentially originated from the medium detecting, and 101 with a predetermined reference value. The motion analyzing unit 102 then analyzes a decession of a motion based on a sign (plas/minus) of an acceleration level that first exceeds the reference value, and further analyzes a strength of the motion by calculating a period during which acceleration levels are above then after rate evalue.

The user action analyzing unit 103 specifies a type of the user's action such as "swing" or "tap", based on the period during which the acceleration levels are above the reference value.

While the motion analyzing und 102 in the first embediment has evaluated the integral of acceleration levels outputted from the motion detecting unit 101, in the present embediment a strength of a motion is analyzed by calculating a period doning which acceleration levels are above the reference value, so that it is unnecessary to calculate the integral of acceleration levels. Hence the A-D converter 203 in the motion detecting unit 101 shown in FIG. 2 can be 3 replaced with an analog comparator.

The procedure of the motion analyzing unit 102 and user scrion analyzing unit 103 of the fourth embodiment is explained below with reference to FIGS, 19 and 20, FIG. 19 shows acceleration curve 1901 outputted, for instance, from 26 the acceleration sensor 302 when the enclosure 303 is swang once in the positive direction of the detection was 306 and then stopped. FIG. 20 shows acceleration curve 2001 outputted, for instance, from the acceleration sensor 302 whost the enclosure 303 is tapped once in the positive 45 direction of the detection axis 306.

In these figures, the vertical axis represents voltage outputted from the acceleration sensor 302, while the horizontal axis represents time.

First reference value a wing Threshold shown by broken lines 1982 and 1983 in PIG. 19 denotes a voltage corresponding to an acceleration level which is normally exceeded when the user swings the enclosure 303. This reference value is set to correspond to 1 G (G decous the acceleration of gravity) in this embediment, although the value may be changed by the user or the operation inducation ompatting device itself. Since a voltage outputted from the acceleration sensor 362 is proportional to an acceleration level, the voltage is multiplied by a certain scale factor to get a value corresponding to 1 G.

First reference value #SwingThreshold shown by broken lines 1902 and 1903 in FIG. 20 is the same as a Swing Thresigned in FIG. 19. Second reference value a Tap Threshold shown by broken lines 2002 and 2003 in FIG. 20 denotes a voltage corresponding to an acceleration level which is normally exceeded when the user taps the enclosure 363. This reference value is set to correspond to 2.5 G in this embodiment, although the value may be changed by the user or the operation indication outputting device itself.

Tap Threshold is set to be larger than Swing Threshold, so that the absolute value of an acceleration level when the user swings the enclosure 303 never exceeds Tap/Threshold.

When acceleration curve 1991 shown in FIG. 19 is outputted from the motion detecting unit 101, the motion as analyzing unit 102 and the user action analyzing unit 103 operate as follows.

The motion analyzing unit 162 sequentially receives acceleration levels represented by acceleration curve 1901 from the motion detecting unit 101 at established time so intervals of 2 msec for example, and judges whether the absolute value of a received acceleration level exceeds Swing Phreshold. On hadging that the absolute value of an acceleration level exceeds SwingThreshold at time TL the motion analyzing unit 102 starts measuring a period during 55 user's action as "tap", since an acceleration curve generated which Swins Breshold is exceeded, and in the meanting analyzes a direction of a motion based on a sign (plus in this example) of the acceleration level at time TI. The motion analyzing unit 102 also judges whether the absolute value of an acceleration level exceeds TapThreshold (see FIG. 20) which is larger than SwingThreshold. Since a type of the user's action associated with acceleration curve 1961 is "swing", there is no acceleration level whose absolute value exceeds Tap Phreshold in FIG. 19.

accorderation level becomes below Swing Threshold at time T2, the motion analyzing unit 102 analyzes a strength of the motion based on period if from TI to T2 during which Swing Threshold is exceeded. The motion analyzing unit 102 then reveals period t1 to the user action analyzing unit 183 and notifies the user action analyzing unit 103 that the absolute value of the acceleration level has become below Swige Threshold

After time T2 the motion analyzing unit 102 continues to indge whether the absolute value of an acceleration level received from the motion detecting unit 101 exceeds Swing-Threshold. On judging that the absolute value of an acculeration level exceeds Swing Threshold at time T3, the motion analyzing unit 102 notifies the user action analyzing unit 103

of this judgement

SwingThreshold is exceeded during period t3 from time 13 to time 14, in spite of which period is not measured this time, since acceleration levels during this period derive from inverse acceleration caused when the user stopped moving the enclosure 303. Then, on judging that the absolate value of an acceleration level becomes below Swing-Threshold at time T4, the motion analyzing anit 102 notifies the user action analyzing unit 103 of this undoument.

Since acceleration curve 1901 in FIG. 19 originates from the user's action of swinging the enclosure 303 once, after T2 there is no acceleration level whose absolute value exceeds SwingThreshold apart from these caused by the inverse acceleration. However, if an acceleration level whose absolute value is above Swing Threshold appears after 14, such an acceleration level is analyzed in counting the number of times the user swings the enclosure 303.

On instructed by the user action analyzing unit 103 to pass the above analysis result to the operation determining unit 104, the motion analyzing unit 102 reveals the direction, strength, and number of occurrence of the motion to the operation determining unit 104.

When restified by the motion analyzing unit 102 that the absolute value of the acceleration level has become below Swing Threshold at time 14, the user action analyzing unit 103 measures period (4 up to a point when the motion analyzing unit 102 notifies that Swing Threshold is exceeded again or a point when a prodetermined period clapses. The predetermined period, such as 100 msec, is a period sufficioni for assuming that there is no more action such as "swing" or "tap" by the user.

Once the predetermined period has Japsed since time T4, the user action analyzing unit 103 analyzes a type of the user's action based on the period, notified by the motion analyzing usic 162, during which Swing Threshold or TanThreshold is exceeded. Concurrently, the user action analyzing and 103 instructs the motion analyzing unit 162 to reveal the analysis result such as the direction of the motion to the operation determining unit 104

If notified by the motion analyzing unit 162 that both Swing Threshold and Tap Threshold were exceeded, the user action analyzing unit 103 proparity judges the type of the as a result of the user tapping the enclosure 303 exceeds both TanThreshold and SwingThreshold without exception.

In the case of acceleration curve 1901 in FIG. 19, the user action analyzing unit 103 is notified by the motion analyzing unit 102 that Swing Threshold was exceeded and of period th during which SwingThoshold was exceeded. Accordingly, once the predmermined period such as 100 orser, has empsed from time T4, the user action analyzing unit 103 analyzes the type of the user's action as "swing" and notifies the opera-Subsequently, on judging that the absolute value of an 55 tion determining unit 104 of the analysis result.

Here, if a period during which SwingThreshold was exceeded is shorter than a fixed first period such as 16 jusec or a period during which TapThreshold was exceeded is imager than a fixed second period such as 20 msec, the user action analyzing unit 103 does not inform the type of the user's action but notifies the operation determining unit 184 of occurrence of a multipotion. Similarly, if the period during which Swing Threshold is exceeded is longer than a fixed third regiod such as 400 msec, the user action analyzing unit 103 notifies the operation determining unit 104 of occurrence of a midfunction instead of informing the type of the user's action

The first period is used here to avoid mistakenly outputage an operation indication when short vibrations which are not intended by the user occur. The third period is used to avoid oristakealy outputting an operation indication when or the like with continuous acceleration of a few seconds. Equally, the second period is used to avoid mistakenly outputting an operation indication in the event of an accident or breakflowe of the operation indication outstating device, since a period during which Tap Threshold is exceeded when the user tops the enclosure 303 with his or her finger(s) is normally in the domain of around a few milliseconds to 10 milliseconds

When, on the other hand, acceleration curve 2001 in PIG. 20 is outputted from the motion detecting unit 101, the $_{28}$ motion analyzing and 102 and the user action analyzing unit 103 operate as follows.

The motion analyzing unit 102 sequentially receives accoleration levels represented by acceleration curve 2001 from the motion detecting unit 101 and indees whether the acabsolute value of a received acceleration level exceeds SwingThreshold. On judging that the absolute value of an recoderation level exceeds Swins/Threshold at time 'T5, the motion analyzing unit 102 starts measuring a period during which Swing Threshold is exceeded. The motion analyzing as smit 102 also analyzes a direction of a motion based on a sign (plus in this example) of the acceleration level at time T5.

Next, the motion analyzing unit 102 judges whether the absolute value of an acceleration level exceeds TapThreshold. On indefing that the absolute value of an acceleration so level exceeds TapThreshold at tune T6, the motion analyzing unit 102 starts measuring a period during which Tan Threshold is exceeded. During the measurement of this period, the motion analyzing unit 102 stops measuring the period during which Swing Throsbold is exceeded. On indg- 45 ing that the absolute value of an acceleration level becomes below TapiThreshold at time T7, the motion analyzing unit 102 reveals period to during which TapThreshold was exceeded to the uses action analyzing unit 163 'The motion analyzing and 102 then resume measuring the period during 50 which Swing Threshold is exceeded until time T8, the measured period thus being the difference of subtracting period to firm period 15. Although this period (15-16) is revealed to the user section analyzing unit 100 along with the notification below Swing Dueshold at time T8, the user action analyzing unit 103 does not use this period for analyzing a type of the user's action. After time T8, there is no acceleration level whose absolute value exceeds Swine Threshold in FIG. 20 On instructed by the user action analyzing unit 103 to notify the above analysis result to the operation determining unit 104, the motion analyzing unit 102 reveals the direction and strength of the motion to the operation determining unit 104 When two periods, namely a period during which Swing-Threshold is exceeded and a period during which 55 Isn'Threshold is exceeded, are measured as in the present case, only the direction and strength corresponding to the

period to during which IspThresbadd was exceeded are revealed to the operation determining unit 104

On notified by the motion analyzing unit 102 that the absolute value of the acceleration level has decreased below SwingThreshold at time 18, the user action analyzing unit 103 measures period is up to a point when the motion analyzing unit 102 notifies that Swing Phreshold is exceeded again or a point when the predatermined period clauses. If the predetermined period classes while there is no petitica-20 Bon from the motion analyzing unit 102 that Swing Threshold is excended again, the user action analyzing unit 103 instructs the motion analyzing unit 102 to summore the analysis result to the operation determining unit 104.

Meanwhile, the user action analyzing unit 103 makes sure the operation indication outputting device is in a running car is that revealed period to during which TapThreshold was exceeded is not langer than the second period, and nurther the operation determining unit 104 that the type of the user's action is "tap".

> The operation determining unit 104 reads an appropriate operation indication from the operation determination table 1201 based on the analysis results given from the motion analyzing auft 102 and user action analyzing trait 103 and outputs the read operation indication to the information processing apparatus via the communicating device 207, in the same way as the first to third embodiments. Note that in the present embodiment "low frequency" and "high frequency" (such as 1202 and 1203) in the operation determination table 1201 are replaced respectively with "swing" and "tan"

> Also, if notified by the user action analyzing unit 163 of occurrence of a malfunction, the operation determining unit 104 does not read an operation indication from the operation determination table 1201 even when it has received an analysis result from the motion analyzing unit 102.

The procedure by the raction analyzing unit 1812 and user action analyzing unit 163 of the fourth embodiment is explained below with reference to FIGS, 21 and 22,

First, the motion analyzing unit 102 initializes each of the following variables to 0 (\$2102)

Variable accFlag shows whether the absolute value of an seccleration level outputted from the mosion detecting unit 101 exceeds a predetermined reference value such as Swing-Threshold.

Variable swingcounter is used to measure a period during which Swing Pareshold is exceeded. Since an acceleration level is outputted per 2 msec in the present embodiment. doubling swingcounter yields a period in milliseconds during which Swing Threshold is exceeded

Variable tapCounter is used to measure a period during which Tap Threshold is exceeded. Doubhag tapcounter yacids a period in milliseconds during which Implifireshold is exceeded.

Variable idleCounter is actually held by the user action that the absolute value of an acceleration level has become se analyzing unit 103, in spine of which it is initialized concurrently with the variables of the motion analyzing unit 102. This variable is used to measure a period during which the reference value (Swing Threshold) is not exceeded after it was once exceeded. Doubling illeconnter yields a period on in milliseconds during which the reference value is not exceeded.

> Variable swingDirect shows a sign of an acceleration level starting from which SwingThreshold is exceeded, and is given a value of variable direct.

Variable tapDirect shows a sign of an acceleration level starting from which Tan Dueshold is exceeded, and is given s value of variable direct in the same way as swing Direct.

Variable direct shows a sign of an acceleration level starting from which a reference value is exceeded. When the sign of the acceleration level is plas, "1" is assigned to direct, while when the sign of the acceleration level is minus. "-I" is assigned to direct, thereby indicating a direction of S

The motion analyzing unit 102 sequentially receives socoleration levels outputted from the motion detecting unit 101 per 2 insec and assigns a received acceleration level to variable acc that shows an acceleration level (\$2104). The 16 than 0 and smaller than TAP_TIME_MAX, the user action motion snatyzing unit 102 then companes the absolute value of acc with first reference value Swing Threshold (\$2106). If the absolute value of see is above Swing Plurshold, the motion analyzing unit 102 sets accFlag at 1 and simularneously instructs the user action analyzing unit 163 to set 45 idleCounter at 0 (\$2108). The user action analyzing unit 103 secondingly sets idleCounter to 0.

The metion analyzing unit 102 next judges whether acc is larger than 0 (\$2110). If acc is larger than 0, the motion analyzing unit 102 sets direct at 1 (S2112), while it ace is no. 26 larger than ft, direct is set at -1 (\$2114).

The ranker analyzing unit 192 further judges whether the absolute value of acc exceeds second reference value TapThreshold (\$2116). When the absolute value of see is on larger than TapThreshold, the motion analyzing unit 102 25 indoes whether swing Direct is 0 (\$2118). If swing Direct is 0. direct is assigned to swingDirect (\$212th, while if swing-Direct is not 0, it is judged whether swingDirect is equal to direct (\$2122). When swingDirect is equal to direct, swingcounter is incremented by 1 (\$2124), while when swingDirect is not equal to direct, the motion analyzing unit 102 judges whether instructed by the user action analyzing unit 103 to reveal an analysis result to the operation determining unit 104 (S2126). If the user action analyzing unit 103 has not yet instructed the motion analyzing and 162 to reveal the analysis result, the procedure returns to step \$2104. Otherwise, the motion analyzing unit 102 informs the operation determining unit 104 of swineDirect that shows a direction of a motion and swingcounter that shows a strength of the motion (\$2128), and complete the procedure.

When judging in step \$2116 that the absolute value of acc exceeds Tap Threshold, the motion analyzing unit 102 judges whether tapDirect is 0 (\$2130) If tapDirect is 0, direct is assigned to tapDirect (S2132), while if tapDirect is not 0, tapilizect is compared with direct (\$2134). When tapDirect is equal to direct, tancounter is incremented by 1 (\$2136). Otherwise, the procedure proceeds to step 52126.

If in step \$2186 the absolute value of acc is inducted as not exceeding SwingThreshold, the motion analyzing unit 102 usiges whether accFing is 1 (\$2138). When accFine is not 1, the procedure mocreds to step \$2126, while when acciffing is 1, the procedure shifts to the user action analyzing unit 103 at such 52202.

Counter by 1 (\$2202) and judges whether idleCounter exceeds specified value IDLE TIME (\$2204). If idle-Counter does not exected IDLE TIME, the procedure returns to step \$2184. Otherwise, the user action analyzing unit 103 instructs the motion analyzing unit 102 to inform the operation determining unit 104 of the analysis result (\$2206) IDLE_TIME referred to here represents a period sufficient for assuming that there is no longer an action such as "swing" or "tap" by the user. IDLE ... TIME is set, for unstance, at 50 corresponding to 100 msec.

the user scripp analyzing unit 103 then indges whether tapDirect is 0 (\$2208). If tapDirect is not 0, it is judged

whether tapo nutter is larger than 0 and smaller than TAP, TIME. MAX that corresponds to the above second period (S2210). TAP_TIME_MAX is set, for instance, at 10 us acceleration levels are outputted per 2 msec from the motion detection unit 101. When tao Counter is either no larger than 0 or no smaller than TAP_TIME_MAX, the user action analyzing unit 103 notifies the operation determining unit 104 of occurrence of a malfunction (\$2212) and returns to step \$2102. When, on the other hand, rapCounter is larger analyzing unit 193 polities the operation determining unit 104 that the type of the user's action is "rap" (\$2214), before returning to step \$2102.

If it is judged in step \$2298 that tantificent is 0, the user action analyzing unit 103 judges whether swingDirect is 0 (\$2216). When swingDirect is 0, the poscedure returns to step \$2102. Otherwise, the user action analyzing unit 103 judges whether swingcounter is larger than SWING. TIME. MIN corresponding to the above first period and smaller than SWING TIME MAX corresponding to the shove third period (S2218), SWING_TIME_MIN and SWING_TIME_MAX are respectively set, for instance, at 5 and 200, given that acceleration levels are outputted per 2 usee from the motion detecting unit 1111,

When in step \$2218 swingcounter is either no larger than SWING_TIME_MIN or no smaller than SWING_TIME_ MAX, the aser action analyzing unit 103 notifies the operation determining unit 104 of occurrence of a uniffunction (\$2220) and returns to step \$2102. Meanwhile, when swingcounter is larger than SWING, TIME, MIN and smaller than SWING_TIME_MAX, the aser action analyzing unit 103 notifies the operation determining and 104 that the type of the user's action is "swing" (\$2222), before returning to step \$2102.

While for ease of explanation the above embodiment has assumed that acceleration levels are omputted from one acceleration sensor, the procedure may also be performed with a plurality of accoleration sousons as in the first to third embraliments.

While in the above embodiment two reference values SwingThreshold and TapThreshold have been used to analyze whether a type of the user's action is "swing," or "tap". more reference values may be used to increase types of the user's actions to be analyzed. By doing so, operation indications outputted from the operation datermining unit 104 can be further diversified

in the above embediment the user action analyzing unit 103 has judged occurrence of a malfunction when a period so during which TapThreshold was exceeded is longer the second period. Alternatively, a value (e.g. 5 G) approximately corresponding to double 'Eap Pareshold may be set as a threshold value, so that when an accoleration level whose absolute value is above this threshold value is desected, the The user action analyzing unit 103 increments lifle- 55 user action analyzing unit 103 judges the acceleration level as deriving from a malfunction caused by the user dropping or bumping the enclosure 303 against something, in the same way, when an acceleration level whose absolute vainc is below 1 G is detected, the user action analyzing unit 183 may judge the acceleration level as deriving from a mal-Something

> While in the first to fourth embodiments the motion detecting unit 101 has used acceleration sensors, the motion detecting unit 191 may instead use angular acceleration 55 sensors. Suppose the acceleration sensor 301 that detects acceleration in the detection axis 305 is raplaced with an angular acceleration sensor. In such a case, when the user

roustes the enclosure 303 by hand, angular acceleration of a mary motion originated from the user's wrist is detected. with the detection axis 305 being the tangential direction.

Applications

The following are applications of the operation indication outputing device of the above embodiments.

1. Application to Mobile Phones

When the user swings or taps a mobile phone into which the operation indication corporating device is incorporated, at the mobile phone can perform an operation such as follows according to an operation indication given from the operation indication outputting device.

(1) When the user taps the mobile phone twice which is emitting an incoming call sound, the mobile phone stops the 13 sound and switches to manner mode (sapping the mobile phone just once may cause a malfunction).

(2) When the user taps the goobile phone twice which is emitting an alarm sound, the mobile obone stops the sound originating a call, the mobile phone stops the call. Thus, the

ages can swiffly cancel a call to a wrong member. (4) To search a telephone directory registered in the mobile phone for a desired number, the mobile phone

switches a display if swung, and calls to the desired number 25 if tunned when the desired number is displayed. (5) When the user swings and then taps the mobile phone which is displaying electronic mail or the like on its display screen, the majoide phone starts and then stops scrolling the

display. (6) An electronic pet displayed on the mobile phone does "shake" when the anobite phone is swang, and does "sit"

when the mobile phone is tapped. (7) A hackbisht gedor on the display screen of the mobile

phone is changed when the mobile phone is swang. (8) The mobile phone produces a different sound depending on how surge and in which direction the user swings the mobile phone and which part of the mobile phone the user

(9) The mobile phone generates modom numbers when so sweng and stops generating the random numbers when tapped, thereby offering a kind of game.

(10) By sending information on the user's action of swinging or tapping the mobile phone to a call destination mobile phone, the mobile phone manipulates a display on a 45 display screen of the call destination mobile phone, has the call distination mobile phone produce an effect sound, or has the call destination mobile phone vibrate

2. Application to Portable Terminals (Computers) When the user swings or taps a portable terminal into 50

which the operation indication outputting device is incorporated, the portable terminal can perform an operation such as follows according to an operation indication given from the operation indication opportung device.

terminal is moved when the user swings the portable terminal, and stopped to select from the menu when the user taps the nortable terminal

(2) When the user wearing a wristwatch-ivoe PDA (Personal Digital Assistance) swings his/her wrist from side 40 to side, latest information is displayed on a display screen of the PDA

3 Application to Remote Controllers

Whon the user swings or taps a remote controller into which the operation indication outputting device is 55 incorporated, the remote controller can output an indication such as follows to a controlled apparatus according to an

operation indication given from the operation indication outputting device (1) TV Remise Controller

A I'V remote controller computs a channel switch indication to a TV when saving from side to side, outputs a volume control indication when swang up and down, and outputs a power off indication when rapped twice.

(2) VCR Remoté Controller

While tape is stopped in a VCR (videocassene recorder), a VCR remote controller outputs a play indication to the VCR when tapped, outputs a fast-forward indication when swang from side to side, and outputs a rewind indication when swung up and down.

While tape is being played in the VCR, the VCR remote controller outputs a stop indication to the VCR when tapped, outputs a fast-forward play indication when sweng from side to side, and outputs a rewind play indication when swung up and down

While tank is being rewound in the VCR, the VCR remote (3) When the user raps the mobile phone twice which is 20 controller outputs a rewind stop indication to the VCR when tapped.

(3) Lighting Remote Controller

A lighting remote controller opiputs a light amount control indication to the lighting when swang from side to side, and outputs a power off indication when tapped. (4) MD (mini disk) Remote Controller

An MD remote controller outputs a power on indication or a nower off indication to an MD when tapped twice, and outputs a track start search indication when swing from side

to side. It should be assed that while in the first to fourth embodiments the motion analyzing unit 162, user action analyzing unit 103, and operation determining unit 104 have performed their respective procedures according to the program stored in the ROM 205 in FIG. 2, this program may be mounted on a storing medium such as a CD-RDM or distributed on the Internet, with it being possible to incerporate the above described function of the present invention into an operation indication outputting device which by itself cannot distinguish twoes of the user's actions as the operation indication outputting device of the present inven-

Although the present invention has been fully described by way of examples with reference to the accompanying drawings, it is to be noted that various changes and modifications will be apparent to those skilled in the art. Therefore, unless such changes and modifications depart from the scope of the present invention, they should be construed as being included therein.

What is claimed is:

1. As operation indication outputting device for outputting an operation indication to an information processing apparates to have the information processing apparatus perform processing based on the outputted operation (1) A selection cursor on a menu displayed on the portable 35 indication, the operation unfection outputing device comprising:

storing means for storing operation indications that each correspond to a combination of a type of a user's action and at least one of a direction, a strongft, and a number of occurrence of a motion of the occurries indication ompuning device caused by the user's action;

morion detecting means for detecting a motion of the operation indication outputting device caused by the user's action:

motion analyzing means for analyzing at least one of a direction, a strength, and a number of occirresce of the detected metion.

user action analyzing means for analyzing a type of the user's action that causes the detected motion; and

outputting means for reading, from the storing means, an operation indirection corresponding to a combination of son markers result by the unition analyzing means and s an analysis result by the user action analyzing means, and outputting the read operation indication to the information processing apparatus.

 The operation indication outputting device of claim 1, wherein the motion detecting means detects acceleration to levels of the motion of the operation indication outputting device over time, sad

wherein the motion analyzing means analyzes at least one of the direction, the strength, and the number of occurrence of the motion by integrating, with respect to time, to secoleration levels outputted from the motion detecting means.

 The operation indication outputting device of claim 2, wherein the user action analyzing mesos includes

a fast I-outier transform analyzing unit for obtaining a zerigeneouy distribution by performing a fast Fourier transform on a curve produced by graphing the acceleration levels outputted from the motion detecting means against time, to analyze the type of the uses 's sector."

4. The operation indication outputing device of claim 3, wherein the user action analyzing useans forther includes an output prohibiting with the prohibiting the outputing means to output the operation indication if a peak value in the obtained frequency distribution is any of the obtained frequency and above a second frequency.

 The operation indication natputting device of claim 2, wherein the user action passyzing means includes

a differential analyzing unit for differentiating, according to a predetermined equation, a curve produced by graphing the acceleration levels omposited from the motion detecting means against time, to analyze the type of the user's action.

 The operation indication outputting device of claim 5, wherein the user action analyzing means forther includes

an output profibiting und for profibiting the outputting owans to output the operation indication if a near value of differential values calcutated by the differential analyzing unit is any of below a first threshold value and above a second threshold value.

 The operation indication corporating device of claim 2, wherein the user action analyzing means includes

a wavelet transform analyzing unit for detecting specific frequency components by performing a wavelet transform on a curve produced by graphing the secocleration levels outputed from the motion detecting meurs against time, to analyze the type of the user's seriem.

8. The operation indication outputting device of claim 7, wherein the storing means further stores operation indications that each correspond in an order of a plurality of types of the user's actions.

wherein the user action analyzing mount further includes. so an action sequence analyzing unit for martyzing types of the user's actions that cause the motion, according to an order in which the detected specific frequency composuents spear, and

wherein the outputting means includes

su order-corresponding operation redicating unit for reading, from the stering means, an operation indication corresponding to an order of the types of the user's actions analyzed by the action sequence analyzing unit, and outputing the read operation indication to the information processing apparams.

The operation indication outputting device of claim 2.

wherein the user action analyzing means includes a time analyzing unit for measuring, for each if a plurality of reference values, time during which the reference value is exceeded by absolute values of a sequence of acceleration levels among the secoleration levels outmitted from the motion detection

means, to analyze the type of the user's action.

10. The operation indication conputting device of chim 9, wherein the user action analyzing means further includes

wherein the user already and the ability the outputting means to output the operation indication if at least one of absolute values of the outputted acceleration levels is any of below a first threatedd value and shows a second threshold value.

 The operation indication outputing device of claim 1, wherein the motion discouragements detects acceleration levels of the unition of the operation indication outputting device over time.

wherem for each of a phradity of reference values, when the reference value is excessed by absolate values for a sequence of acceleration levels among the acceleration tensities unalyzing means analyzes a sign of an accelcration unalyzing means analyzes a sign of an accelcration level whose a shallow evide. First exceeds, the reference value in the sequence of acceleration levels, and measures time during which he reference value is excessed by the absolute values of the sequence of acceleration levels, thereby analyzing a base one of the direction, the errorgit, and the number of occurrence of the remain, and

wherein the user action analyzing means analyzes the type of the user's action based on the time measured by the motion analyzing means.

12. The operation indication outpatting device of claim

wherein the plurality of reference values are made up of a first reference value and a second reference value larger than the first reference value, and

wherein the user action analyzing means includes an output prediction and for prohibing the outputting means to output the operation indication, any of time during which the first reference value is exceeded is shorter than predestrealised first time and it lime thring which the second reference value is exceeded is longer than predestrealised second time. It has been also also that the contraction of the con

12. wherein the first reference value is set at a value corresponding to an acceleration level which is to be detected when the user swings the operation indication outputting device.

wherein the second reterence value is set at a value corresponding to an acceleration level which is to be detected when the user taps the operation indication outputting device, and

wherein the user action analyzing means analyzes whether the type of the user's action is "swing" or "tap".

14. The operation indication outputting device of chim 1, wherein the motion detecting means detects angular acceteration levels of the motion of the operation indication outputting device over time, and

wherein the nistion analyzing means analyzes at least one of the direction, the strength, and the number of occurrence of the motion by integrating, with respect to time, the angular acceleration levels outputted from the motion detection means.

15. The operation indication outputting device of claim

wherein the user action analyzing means includes

a last Fourier transform analyzing unit for obtaining a frequency distribution by performing a fast Fourier it transform on a curve produced by graphing the angular acceleration levels outputted from the motion detecting means acainst time, to analyze the

type of the user's action.

16. The operation indication outputing device of claim 1, 45 wherein the motion detecting means detects angular acceleration levels of the motion of the operation indication outputting device over time.

wherein for each of a plutality of reference values, when the reference value is exceeded by absolute values of a sequence of angular acceleration levels among the angular acceleration levels outgutted from the motion detecting means, the motion analyzing means analyzes a sign of an angular acceleration level whose absolute value first exceeds the reference value in the second of angular acceleration levels, and measures time duriing which the reference value in the surface of the absolute values of the sequence of angular acceleration levels, thereby analyzing at least one of the direction, the strength, and the number of occurrence of the motion, and

wherein the mer action analyzing means analyzes the type of the user's action based on the time measured by the motion analyzing means.

17. The operation indication outputting device of claim

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wherein the plurality of reference values are made up of a first reference value and a second reference value

larger than the first reference value, and wherein the user action analyzing means includes

an output probibiting unit for probibiting the nutputting means in output the operation indication, any of if time during which the lists reference value is exceeded is shorter than predetermined first time and 45 if time during which the second reference value is exceeded is longer than predetermined second time.

18. The operation indication outputing device of claim 1, wherein the operation indication outputting device is

incorporated into a mobile phone that is the information

processing apparatus, and wherein a processing mode of the mobile phone is

changed according to the operation indication outputted from the outputting means. 19. A mobile phone that incorporates an operation indication outputting device for outputting an operation indication so the mobile phone to have the mobile phone perform processing based on the outputted operation indication, the operation indication outputted operation indication, the

sterring means for storing operation indications that each correspond to a continuation of a type of a user's action and at least one of a direction, a strength, and a number of occurrence of a motion of the operation indication outputing device earnoad by the user's action;

motion detecting means for detecting a motion of the operation indication outputting device caused by the user's action;

motion analyzing means for analyzing at least one of a direction, a strength, and a number of occurrence of the detected motion;

user action analyzing means for analyzing a type of the user's action that causes the distected musion; and

outputting means for reading, from the storing means, an operation indication corresponding to a combination of as analysis result by the metion analyzing means and an analysis result by the user section analyzing means, and outputting the read operation indication to the mobile phone.

wherein a processing mode of the mobile phone is changed according to the operation indication outputted from the outputing means.

20. A computer-cacadable storing motisms storing a polygram executed by an operation inheating encurpating device that is equipped with a detecting unit for descering a metion of the operation judiciation outputting device caused by a vaser's action and ratgusts an operation indication to surpressessing apparatus to have the information of information processing apparatus perform processing based on the outputted operation indication, the program computed operation indication, the program computed.

a motion analyzing step for analyzing at least one of a direction, a strength, and a number of occurrence of the motion detected by the detecting unit;

a user action analyzing step for analyzing a type of the user's action that causes the detected mixing and

an unputting step for mediting, from an storing unit which stores operation indiscisions that each correspond to a combination of a type of the user's action and at least one of a citiection, a strength, and a number of occurrence of a mexicon of the operation indication outputting device crassed by the user's action, an operation indication corresponding to a combination of an analysis result obtained in the motion analyzing step and an analysis result obstated in the new action analyzing step, and outputting the read operation indication to the information processing apparation.